

Endogenous vs Exogenous Fluctuations: Unveiling the Impact of Heterogeneous Expectations

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Computational Economics



Where We Come From

Gusella & Ricchiuti (2024, Journal of Evolutionary Economics):

- Heterogeneous Agent Model (chartists & fundamentalists) → linear state-space form
- Kalman filter estimation + Monte Carlo simulation
- Evidence of **endogenous damped cycles** in S&P 500
- Rolling-window forecasting: behavioral model vs. random walk

Key limitation:

- Population shares (δ , $1 - \delta$) are **fixed**: chartists and fundamentalists always coexist in constant proportions
- Fails to capture **regime switching** — in reality, investors switch strategies over time



This paper: extend to a nonlinear Markov-switching framework



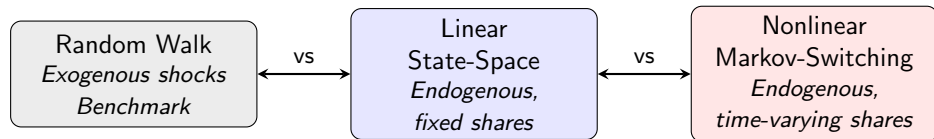
Research Questions

1. Do financial market fluctuations arise from **endogenous** behavioral dynamics or from **exogenous** shocks?
2. Does **nonlinear** (regime-switching) endogenous instability offer greater explanatory power than **linear**, globally stable dynamics?
3. Which specification delivers superior **out-of-sample forecasting** performance?

Data: S&P 500 monthly data, January 1990 – December 2019



Three Competing Models



RW

$p_t = p_{t-1} + \varepsilon_t$
No behavioral content

LSSM

Fixed δ + Kalman filter
Damped cycles

NLMS

Time-varying regime
probs.
Local instability



Estimation: Kalman Filter vs. EM Algorithm

Kalman Filter (Path A)

Latent state: **continuous** ($B_t^c \in \mathbb{R}$)

- *Predict*: project B_t^c forward via transition eq.
- *Update*: correct using forecast error on p_t
- Likelihood recovered via prediction error decomposition
- Exact under Gaussianity & linearity

EM Algorithm (Path B)

Latent state: **discrete** ($s_t \in \{f, c\}$)

- *E-step*: compute regime probabilities given current params (Hamilton filter)
- *M-step*: update params maximizing weighted likelihood
- Iterates until convergence
- Guaranteed \uparrow likelihood at each step

Both are **frequentist** — no prior, no posterior.

Difference from Lux (2018, 2021): Bayesian particle/MCMC filters.



Monte Carlo Simulation: Why and How

Why? MLE on small-to-medium samples is sensitive to local optima and starting values — a single optimization run may not find the global maximum.

How?

- Draw **1000 random starting points** for the parameters
- Run Kalman (or EM) estimation from each starting point
- Retain the solution with the **highest likelihood**
- Report mean and confidence intervals across replications

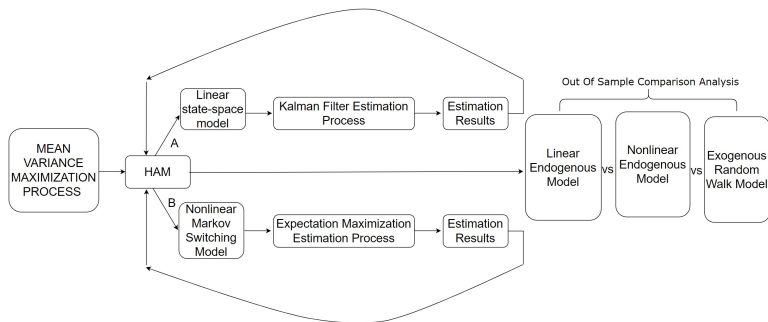
What it is not:

- Not a Bayesian procedure — the 1000 draws are starting points, not posterior samples
- Not a bootstrap — we simulate from the model, not from the data

Robustness check against local optima, not a source of uncertainty quantification



Methodology



Path A: HAM \rightarrow linear state-space \rightarrow Kalman filter estimation \rightarrow out-of-sample comparison.

Path B: HAM \rightarrow nonlinear Markov-switching \rightarrow EM estimation \rightarrow out-of-sample comparison.



The HAM Setup

Standard mean-variance optimizing agents; two types:

Asset pricing equation:

$$p_t = \delta E_t^f(p_{t+1}) + (1 - \delta) E_t^c(p_{t+1})$$

Fundamentalists (anchor to Gordon-model fundamental p_t^f):

$$E_t^f(p_{t+1}) = p_t^f$$

Chartists (extrapolate past price changes, first-order heuristic):

$$E_t^c(p_{t+1}) = p_t^f + \beta(p_{t-1} - p_{t-2}), \quad \beta > 0$$

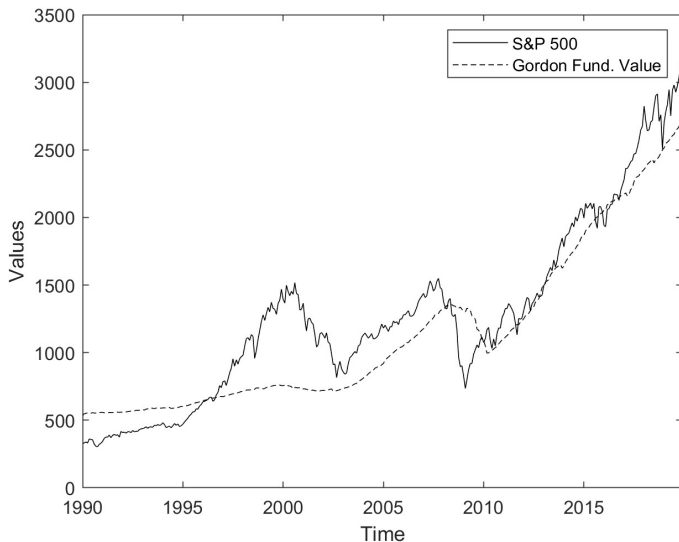
Substituting:

$$p_t = p_t^f + \underbrace{(1 - \delta) \beta (p_{t-1} - p_{t-2})}_{B_t^c}$$

⇒ Price deviates from fundamental through the **unobserved belief** B_t^c



Data: S&P 500 and Fundamental Value



Path A: Linear State-Space Form

Substituting into the belief function of chartists and using the random-walk fundamental:

$$B_t^c = \beta(1 - \delta) B_{t-1}^c - \beta(1 - \delta) B_{t-2}^c + \varepsilon_t$$

Measurement equation:

$$p_t = p_t^f + [(1 - \delta) \ 0] \begin{bmatrix} B_t^c \\ B_{t-1}^c \end{bmatrix}$$

Transition equation:

$$\begin{bmatrix} B_t^c \\ B_{t-1}^c \end{bmatrix} = \underbrace{\begin{pmatrix} a_{11} & a_{12} \\ 1 & 0 \end{pmatrix}}_A \begin{bmatrix} B_{t-1}^c \\ B_{t-2}^c \end{bmatrix} + \begin{bmatrix} \varepsilon_t \\ 0 \end{bmatrix}$$

with $a_{11} = \beta(1 - \delta)$, $a_{12} = -\beta(1 - \delta)$.

Cyclical condition (complex eigenvalues of A):

$$0 < \beta(1 - \delta) < 4$$

If $\sqrt{\beta(1 - \delta)} < 1$: *damped* endogenous fluctuations.

Estimation: Kalman filter + Monte Carlo MLE (1000 repetitions)



Path B: Nonlinear Markov-Switching Form

Agent shares δ and $(1 - \delta)$ are **time-varying**, governed by a first-order Markov chain $s_t \in \{f, c\}$.

Working in first differences:

$$\Delta p_t = \varepsilon_t(s_t) + [a_{11} \Delta p_{t-1} + a_{12} \Delta p_{t-2}](s_t)$$

State transition matrix:

$$\begin{pmatrix} p_{ff} & p_{fc} \\ p_{cf} & p_{cc} \end{pmatrix}, \quad p_{ff} + p_{fc} = 1, \quad p_{cf} + p_{cc} = 1$$

Regime f (fundamentalist):

price tracks p_t^f

Regime c (chartist):

price driven by past values

The **filtered regime probability** serves as a time-varying proxy for the weight assigned to each behavioral strategy.

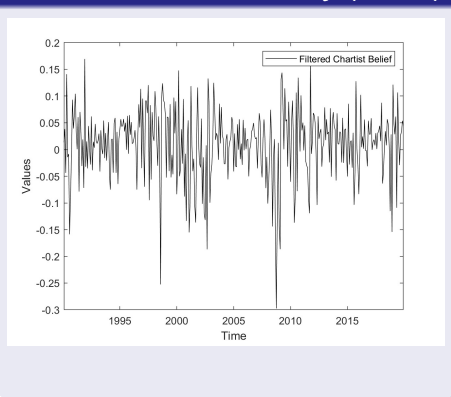
Estimation: Expectation-Maximization (EM) algorithm + Monte Carlo (1000 repetitions)

In-Sample Results: Linear Model (LSSM)

Cyclical Parameters			
	a_{11}	a_{12}	
Values	0.5398*** [0.537, 0.542]	-0.5398*** [-0.542, -0.537]	
	δ	$1 - \delta$	β
Values	0.69	0.31***	1.74
Cycl. cond.	Fulfilled		
Eigenvalues	$-0.270 \pm 0.683 i$		
Modulus	0.73 (<i>damped</i>)		

- 69% fundamentalists, 31% chartists
- **Damped cycles:** modulus $0.73 < 1$
- $B_t^c > 0$ in booms; sharp \downarrow at GFC

Filtered chartist belief B_t^c (Fig. 3)

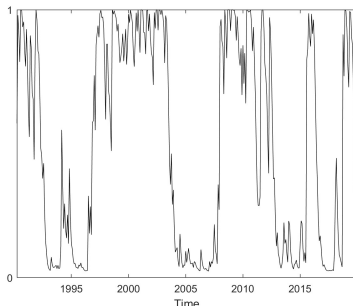


In-Sample Results: Nonlinear Model (NLMS)

Cyclical Parameters		
	a_{11}	a_{12}
Values	0.04*** [0.03, 0.05]	-0.04*** [-0.05, -0.03]
Transition probabilities		
$p_{ff} = 0.9425$	$p_{fc} = 0.0575$	
$p_{cf} = 0.0833$	$p_{cc} = 0.9167$	
Cycl. cond.	Fulfilled	
Eigenvalues	$-0.020 \pm 0.199 i$	
Modulus	0.46 (<i>damped</i>)	

- High persistence: agents stay in same regime
- Chartist regime \uparrow at dot-com & GFC
- β time-varying: spikes & reverts

Chartist regime prob (Fig. 4)



Rolling-Window Out-of-Sample Design

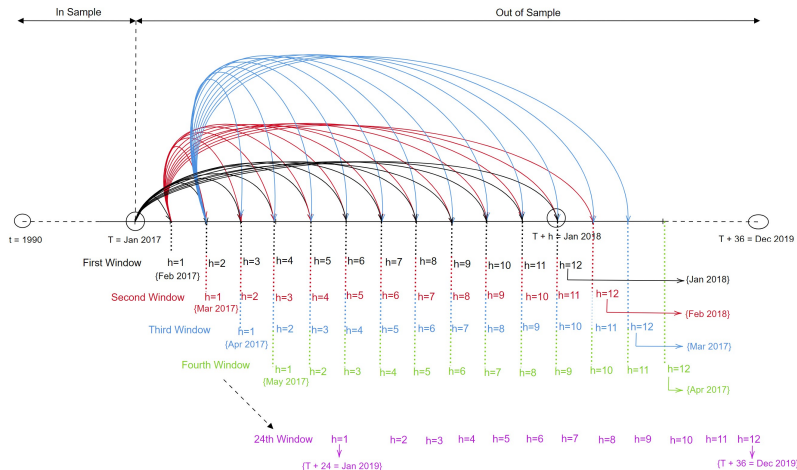
- **In-sample:** Jan 1990 – Dec 2016 **Out-of-sample:** Jan 2017 – Dec 2019
- **Rolling window:** 325 monthly observations; window shifts by 1 each step
- **Forecast horizons:** $h = 1, 2, \dots, 12$ months
 - Short-run: $h = 1, 2, 3, 4$
 - Medium-run: $h = 5, 6, 7, 8$
 - Long-run: $h = 9, 10, 11, 12$
- Forecast accuracy: **RMSE** and **MAE** ratios + **Diebold-Mariano** test

Ratios reported:

- Table 4: $\text{RMSE(LSSM)} / \text{RMSE(RW)} > 1$ means RW wins
- Table 5: $\text{RMSE(NLMS)} / \text{RMSE(LSSM)} < 1$ means NLMS wins
- Table 6: $\text{RMSE(NLMS)} / \text{RMSE(RW)} < 1$ means NLMS wins



Rolling-Window Out-of-Sample Design



At each step, the model is re-estimated on the most recent 325 observations and forecasts are generated for $h = 1, \dots, 12$ months ahead.



Comparing Forecast Accuracy: Diebold-Mariano Test

Question: are the differences in forecast accuracy statistically significant, or just due to sampling variability?

Define the **loss differential** between two forecasts (e.g. NLMS vs. LSSM):

$$d_{T+h} = (\varepsilon_{T+h|T}^L)^2 - (\varepsilon_{T+h|T}^{NL})^2$$

Null hypothesis: equal predictive accuracy

$$H_0 : \mathbb{E}[d_{T+h}] = 0 \quad \forall (T + h)$$

DM test statistic:

$$DM = \frac{\bar{d}}{\sqrt{\hat{\sigma}_d^2/k_h}} \xrightarrow{d} \mathcal{N}(0, 1)$$

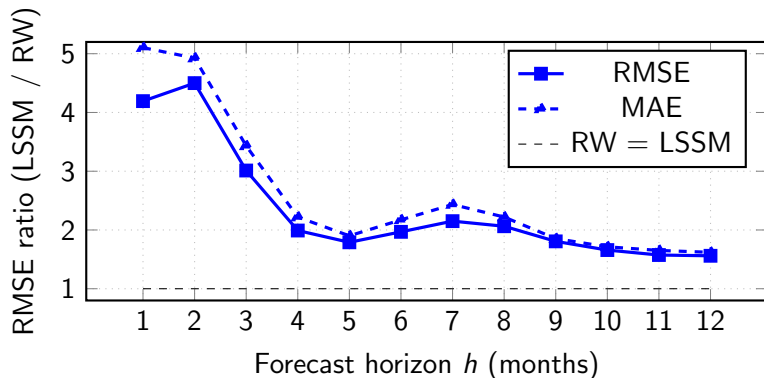
where \bar{d} is the sample mean of d_{T+h} , $\hat{\sigma}_d^2$ its long-run variance, and $k_h = 24$ the number of forecast observations.

- Applied to all three pairwise comparisons (Tables 4, 5, 6)
- Rejection of $H_0 \Rightarrow$ the performance gap is **statistically significant**
- Results robust at 1% level for NLMS vs. LSSM at all horizons



Out-of-Sample: LSSM vs. Random Walk (RMSE ratio)

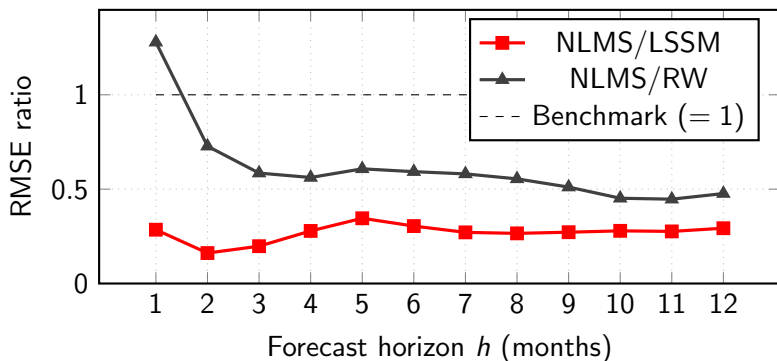
Ratio > 1 : RW outperforms LSSM at all horizons; gap narrows as h grows.



Interpretation: LSSM converges toward RW at long horizons — consistent with its mean-reverting structure.



Out-of-Sample: NLMS vs. LSSM and RW (RMSE ratio)



- **NLMS vs LSSM:** ratio $\approx 0.15\text{--}0.35$ at *all* h (1% sig.)

- **NLMS vs RW:** beats RW from $h = 2$; ratio $\rightarrow 0.45$ at $h = 12$



Summary of Out-of-Sample Results

Model	Short-run	Medium-run	Long-run
LSSM vs RW	RW wins	RW wins	RW wins*
NLMS vs LSSM	NLMS wins	NLMS wins	NLMS wins
NLMS vs RW	\approx tied	NLMS wins	NLMS wins

* LSSM converges toward RW performance at long horizons

Bottom line: nonlinear endogenous dynamics \succ linear endogenous dynamics \succ exogenous RW (at medium/long horizons)



Comparison with Gusella & Ricchiuti (2024)

	GR (2024)	DGR (2025)
Agent shares	Fixed (δ constant)	Time-varying (Markov chain)
Estimation	Kalman filter (MLE)	EM algorithm
Models compared	LSSM vs. RW	NLMS vs. LSSM vs. RW
Reaction coeff. β	Constant	Time-varying
Regime detection	No	Yes (filtered probs.)
Out-of-sample	LSSM beats RW (medium/long)	NLMS beats both (from $h = 2$)

Novelty of DGR (2025):

- First paper to compare *linear vs. nonlinear* endogenous models against the RW in a state-space out-of-sample forecasting context
- Markov-switching captures **local instability** episodes (dot-com, GFC)



Conclusions

1. **Endogenous fluctuations confirmed:** both LSSM and NLMS exhibit complex eigenvalues, supporting behavioral heterogeneity as the driver of financial instability.
2. **Nonlinearity matters for forecasting:** the Markov-switching model substantially outperforms the linear behavioral model at all horizons.
3. **Beating the random walk:** NLMS outperforms the RW from $h = 2$ onward; advantage grows with the horizon, reaching $\sim 50\%$ RMSE reduction at $h = 12$.
4. **Regime interpretation:** trend-following dominates during market stress; fundamentalist behavior guides recovery.

Future extensions: crypto currencies, additional heuristics (noise traders, contrarians); exchange rate market; multivariate models linking financial and real sectors.